

PACs for Industrial Control, the Future of Control

For the last decade a passionate debate has raged about the advantages and disadvantages of PLCs (programmable logic controllers) compared to PC-based control. As the technological differences between PC and PLC wane, with PLCs using commercial off the shelf (COTS) hardware and PC systems incorporating real-time operating systems, a new class of controllers, the PAC is emerging. PAC, a new acronym created by Automation Research Corporation (ARC), stands for Programmable Automation Controller and is used to describe a new generation of industrial controllers that combine the functionality of a PLC and a PC. The PAC acronym is being used both by traditional PLC vendors to describe their high end systems and by PC control companies to describe their industrial control platforms.

The “80-20” Rule

During the three decades following their introduction, PLCs have evolved to incorporate analog I/O, communication over networks, and new programming standards such as IEC 61131-3. However, engineers create 80 percent of industrial applications with digital I/O, a few analog I/O points, and simple programming techniques. Experts from ARC, Venture Development Corporation (VDC), and the online PLC training source PLCS.net estimate that:

- 77% of PLCs are used in small applications (less than 128 I/O)
- 72% of PLC I/O is digital
- 80% of PLC application challenges are solved with a set of 20 ladder-logic instructions

Because 80 percent of industrial applications are solved with traditional tools, there is strong demand for simple low-cost PLCs. This has spurred the growth of low-cost micro PLCs with digital I/O that use ladder logic. It has also created a discontinuity in controller technology, where 80 percent of applications require simple, low cost controllers and 20 percent relentlessly push the capabilities of traditional control systems. The applications that fall within the 20 percent are built by engineers who require higher loop rates, advanced control algorithms, more analog capabilities, and better integration with the enterprise network.

In the 80s and 90s, these “20 percenters” evaluated PCs for industrial control. The PC provided the software capabilities to perform advanced tasks, offered a graphical rich programming and user environment, and utilized COTS components allowing control engineers to take advantage of technologies developed for other applications. These technologies include floating point processors; high speed I/O busses, such as PCI and Ethernet; non-volatile data storage; and graphical development software tools. The PC also provided unparalleled flexibility, highly productive software, and advanced low-cost hardware.

However, PCs were still not ideal for control applications. Although many engineers used the PC when incorporating advanced functionality, such as analog control and simulation, database connectivity, web based functionality, and communication with third party devices, the PLC still ruled the control realm. The main problem with PC-based control was that standard PCs were not designed for rugged environments.

The PC presented three main challenges:

- **Stability:** Often, the PC's general-purpose operating system was not stable enough for control. PC-controlled installations were forced to handle system crashes and unplanned rebooting.
- **Reliability:** With rotating magnetic hard drives and non-industrially hardened components, such as power supplies, PCs were more prone to failure.
- **Unfamiliar Programming Environment:** Plant operators need the ability to override a system for maintenance or troubleshooting. Using ladder logic, they can manually force a coil to a desired state, and quickly patch the affected code to quickly override a system.

However, PC systems require operators learn new, more advanced tools. Although some engineers use special industrial computers with rugged hardware and special operating systems, most engineers avoided PCs for control because of problems with PC reliability. In addition, the devices used within a PC for different automation tasks, such as I/O, communications, or motion, may have different development environments.

So the “twenty percenters” either lived without functionality not easily accomplished with a PLC or cobbled together a system that included a PLC for the control portion of the code and a PC for the more advanced functionality. This is the reason many factory floors today have PLCs used in conjunction with PCs for data logging, connecting to bar code scanners, inserting information into databases, and publishing data to the Web. The big problem with this type of setup is that these systems are often difficult to construct, troubleshoot and maintain. The system engineer often is left with the unenviable task of incorporating hardware and software from multiple vendors, which poses a challenge because the equipment is not designed to work together.

Building a Better Controller

With no clear PC or PLC solution, engineers with complex applications worked closely with control vendors to develop new products. They requested the ability to combine the advanced software capabilities of the PC with the reliability of the PLC. These lead users helped guide product development for PLC and PC-based control companies.

The software capabilities required not only advanced software, but also an increase in the hardware capabilities of the controllers. With the decline in world-wide demand for PC components, many semiconductor vendors began to redesign their products for industrial applications. Control vendors today are incorporating industrial versions of floating point

processors, DRAM, solid-state storage devices such as CompactFlash, and fast Ethernet chipsets into industrial control products. This enables vendors to develop more powerful software with the flexibility and usability of PC-based control systems that can run on real-time operating systems for reliability.

The resulting new controllers, designed to address the “20 percent” applications, combine the best PLC features with the best PC features. Industry analysts at ARC named these devices programmable automation controllers, or PACs. In their “Programmable Logic Controllers Worldwide Outlook” study, ARC identified five main PAC characteristics. These criteria characterize the functionality of the controller by defining the software capabilities:

- “Multi-domain functionality, At least 2 of logic, motion, PID control, drives, and process on a single platform.” Except for some variations in I/O to address specific protocols like SERCOS; logic, motion, process, and PID are simply a function of the software. For instance, motion control is a software control loop which reads digital inputs from a quadrature encoder, performs analog control loops, and outputs an analog signal to control a drive.
- “Single multi-discipline development platform incorporating common tagging and a single database for access to all parameters and functions.” Because PACs are designed for more advanced applications such as multi-domain designs, they require more advanced software. In order to make system design efficient, the software must be a single integrated software package instead of disparate software tools which are not engineered to seamlessly work together.
- “Software tools that allow the design by process flow across several machines or process units, together with IEC61131-3, user guidance, and data management.” Another component that simplifies system design is high level graphical development tools that make it easy to translate an engineer’s concept of the process into code that actually controls the machine.
- “Open, modular architectures that mirror industry applications from machine layouts in factories to unit operations in process plants.” Because all industrial applications require significant customization, the hardware must offer modularity so the engineer can pick and choose the appropriate components. The software must enable the engineer to add and remove modules to design the required system.
- “Employ de-facto standards for network interfaces, languages, etc., such as TCP/IP, OPC & XML, and SQL queries.” Communication with enterprise networks is critical for modern control systems. Although PACs include an Ethernet port, the software for communication is the key to trouble-free integration with the rest of the plant.

Two Approaches to Software

While software is the key difference between PACs and PLCs, vendors vary in their approach to providing the advanced software. They typically start with their existing control software and work to add the functionality, reliability, and ease-of-use required to

program PACs. Generally, this creates two camps of PAC software providers: those with a background in PLC control and those with a background in PC control.

Software Based On PLC Philosophy

Traditional PLC software vendors start with a reliable and easy-to-use scanning architecture and work to add new functionality. PLC software follows a general model of scanning inputs, running control code, updating outputs, and performing housekeeping functions. A control engineer is concerned only with the design of the control code because the input cycles, output cycles, and housekeeping cycles are all hidden. With much of the work done by the vendor, this strict control architecture makes it easier and faster to create control systems. The rigidity of these systems also eliminates the need for the control engineer to completely understand the low-level operation of the PLC to create reliable programs. However, the rigid scanning architecture which is the main strength of the PLC, can also make it inflexible. Most PLC vendors create PAC software by adding into the existing scanner architecture new functionality such as Ethernet communication, motion control, and advanced algorithms. However, they typically maintain the familiar look and feel of PLC programming and the inherent strengths in logic and control. The result is PAC software generally designed to fit specific types of applications such as logic, motion, and PID, but is less flexible for custom applications such as communication, data logging, or custom control algorithms.

Software Based On PC Philosophy

Traditional PC software vendors start with a very flexible general-purpose programming language, which provides in-depth access to the inner workings of the hardware. This software also incorporates reliability, determinism, and default control architectures. Although engineers can create the scanner structure normally provided to the PLC programmer, they are not inherent to PC-based control software. This makes the PC software extremely flexible and well suited for complex applications that require advanced structures, programming techniques, or system level control but more difficult for simple applications.

The first step for these vendors is to provide reliability and determinism, which are often not available in a general-purpose operating system such as Windows. This is accomplished through real-time operating systems (RTOS) such as Phar Lap from Ardenne (formerly Venturcom) or VxWorks from Wind River. These RTOSs provide the capability to control all aspects of the control system, from the I/O read and write rates to the priority of individual threads spawned on the controller. These vendors then add abstractions and I/O read/write structures to make it simpler for engineers to build reliable control applications. The result is flexible software suited for custom control, data logging, and communication but lacking the familiar PLC programming architectures, making application development more demanding.

Vision and Measurements in PACs

Many industrial applications collect high speed measurements for vibration or power quality applications. The collected data is used to monitor the condition of rotating

machinery, determine maintenance schedules, identify motor wear, and adjust control algorithms. The data is normally collected using specialized data acquisition systems or stand alone instrumentation and is incorporated into a control system using a communication bus. PACs can directly take high accuracy measurements at millions of samples per second, which are then passed directly into their control systems for immediate processing.

Engineers also can incorporate vision into their control systems. Vision is an area of automation that has gained a lot of momentum in the last decade. In a manufacturing environment, there are many flaws or mistakes that can be identified through visual inspection that are difficult to detect using traditional measurement techniques. Common applications include part inspection for manufacturing or assembly verification, such as checking for correct component placement on a circuit board, optical character recognition (OCR) to examine date codes or to sort products, and optical measurements to find flaws in products or for sorting based on quality criteria. Many plants currently use stand-alone smart cameras that need to communicate to the manufacturing process controller.

PACs eliminate the need for custom hardware

Although PACs represent the latest in programmable controllers, the future for PACs hinges on the incorporation of embedded technology. One example is the ability to use software to define hardware. Field Programmable Gate Arrays (FPGAs) are electronic components commonly used by electronics manufacturers to create custom chips, allowing intelligence to be placed in new devices. These devices consist of configurable logic blocks that can perform a variety of functions, programmable interconnects that act as switches to connect the function blocks together, and I/O blocks that pass data in and out of the chip. By defining the functionality of the configurable logic blocks and the way they are connected to each other and to the I/O, electronics designers can create custom chips without the expense of producing a custom ASIC. FPGAs are comparable to having a computer that literally rewires its internal circuitry to run your specific application.

FPGA technology has only been available to hardware designers who were proficient in low level programming languages like VHDL. However, controls engineers today can use FPGA to create custom control algorithms that are downloaded onto FPGA chips. This capability enables engineers to incorporate extremely time-critical functions to hardware such as limit and proximity sensor detection and sensor health monitoring. Because the control code runs directly in silicon, it is possible for engineers to quickly create applications that incorporate custom communication protocols or high speed control loops: up to 1 MHz digital control loops and 200 kHz analog control loops.